

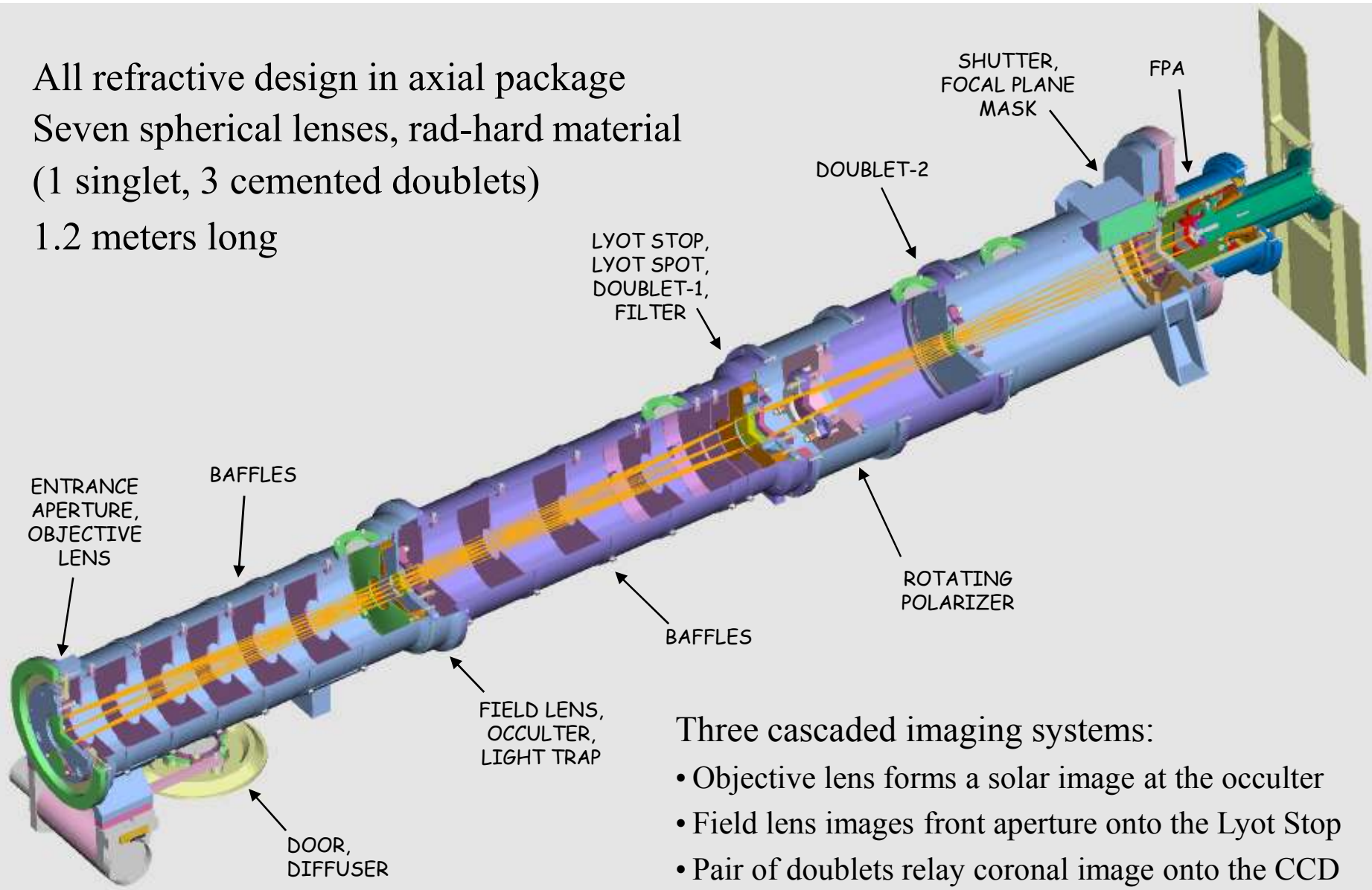
# **COR1 Current Status and Future Plans**

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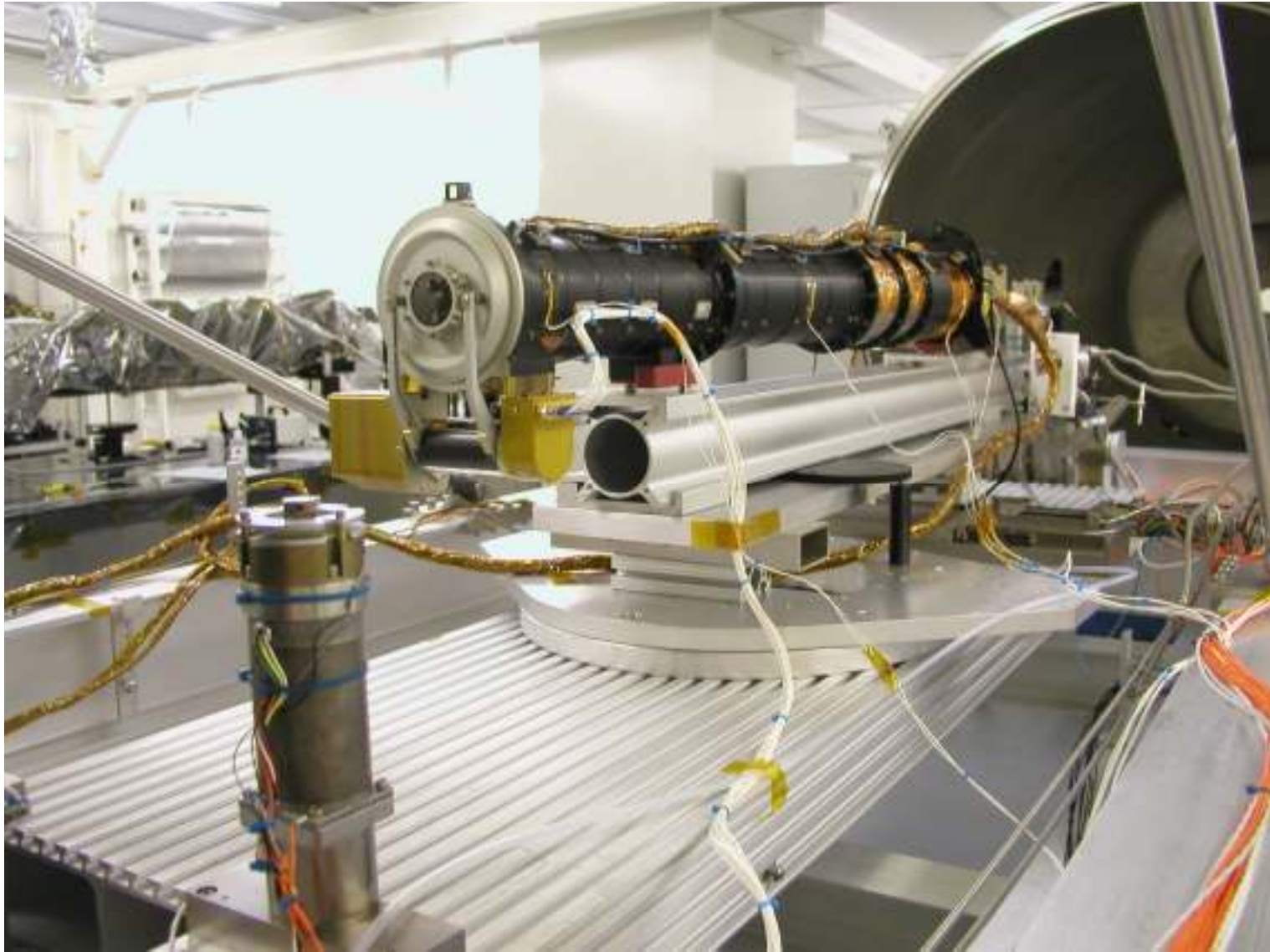
5<sup>th</sup> SECCHI Consortium Meeting  
March 5-8, 2007  
Orsay, France

All refractive design in axial package  
Seven spherical lenses, rad-hard material  
(1 singlet, 3 cemented doublets)  
1.2 meters long



Three cascaded imaging systems:

- Objective lens forms a solar image at the occulter
- Field lens images front aperture onto the Lyot Stop
- Pair of doublets relay coronal image onto the CCD

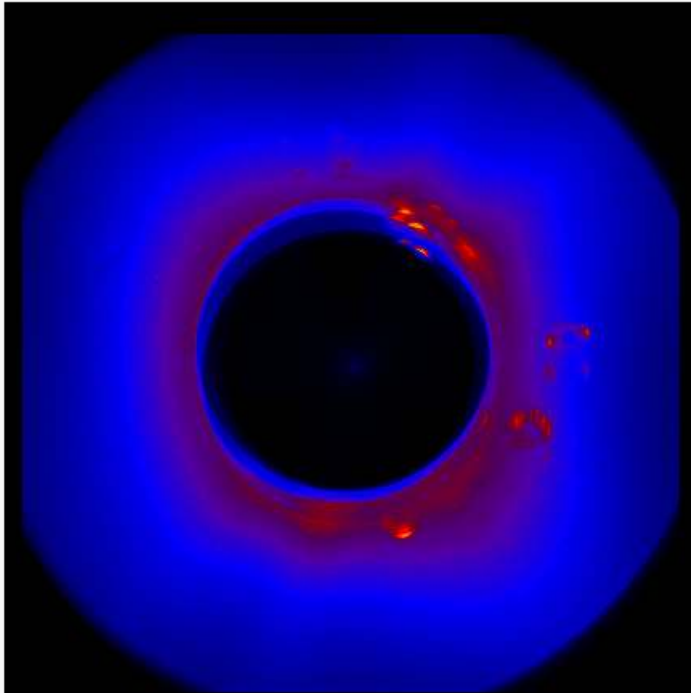




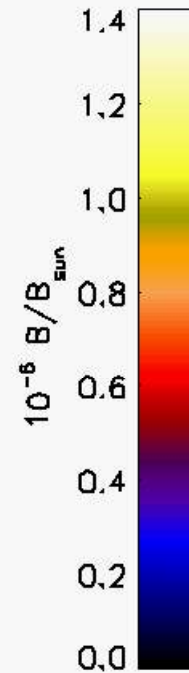
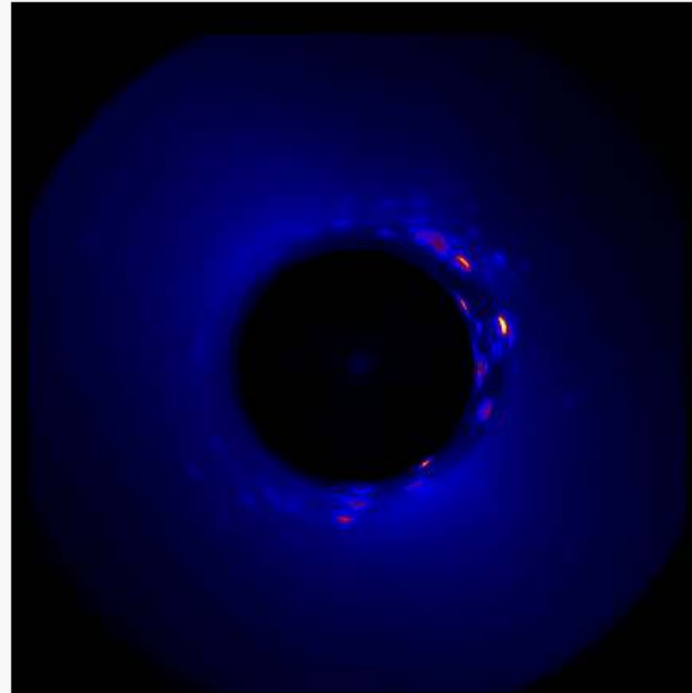


# Scattered Light (preflight)

COR-1A

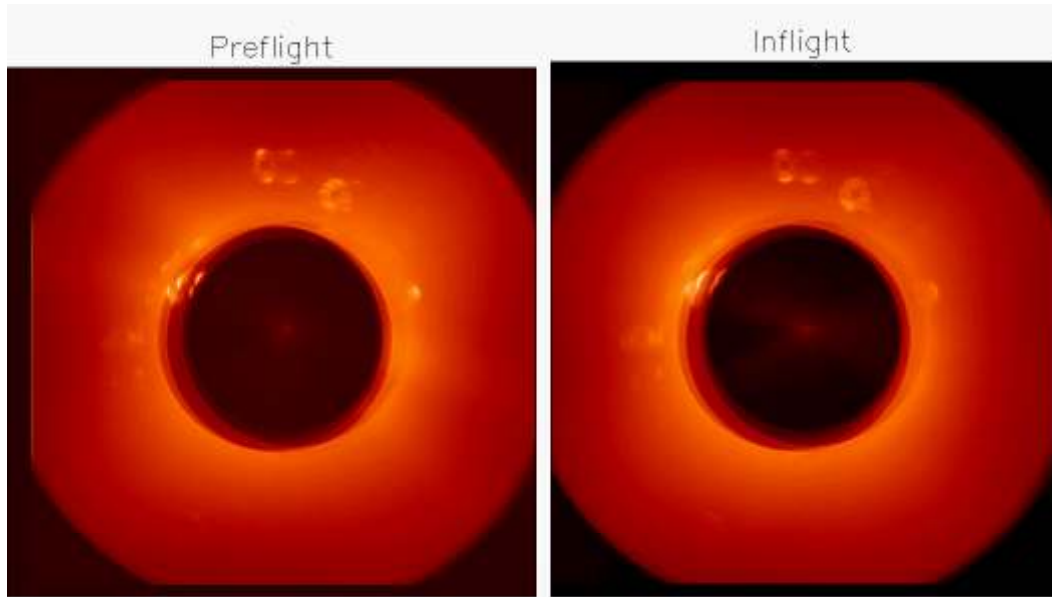


COR-1B



- Overall scattered light levels are much better than the  $10^{-6} B/B_{\text{sun}}$  requirement.
- Small areas with higher scatter due to features on front surface of field lens.

# Inflight Comparison

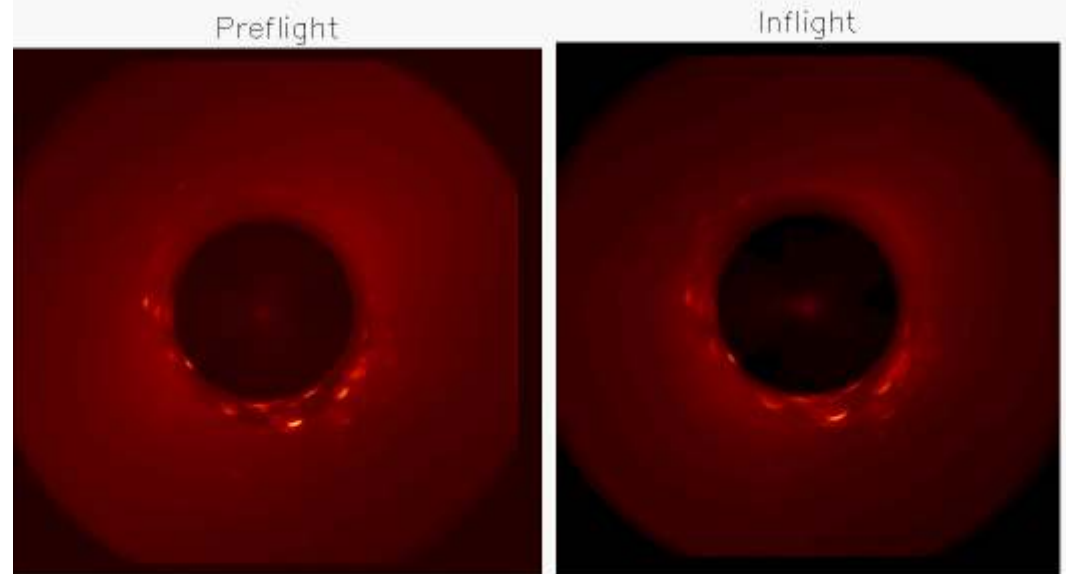


*Inflight scattered light levels match the predictions from preflight testing.*

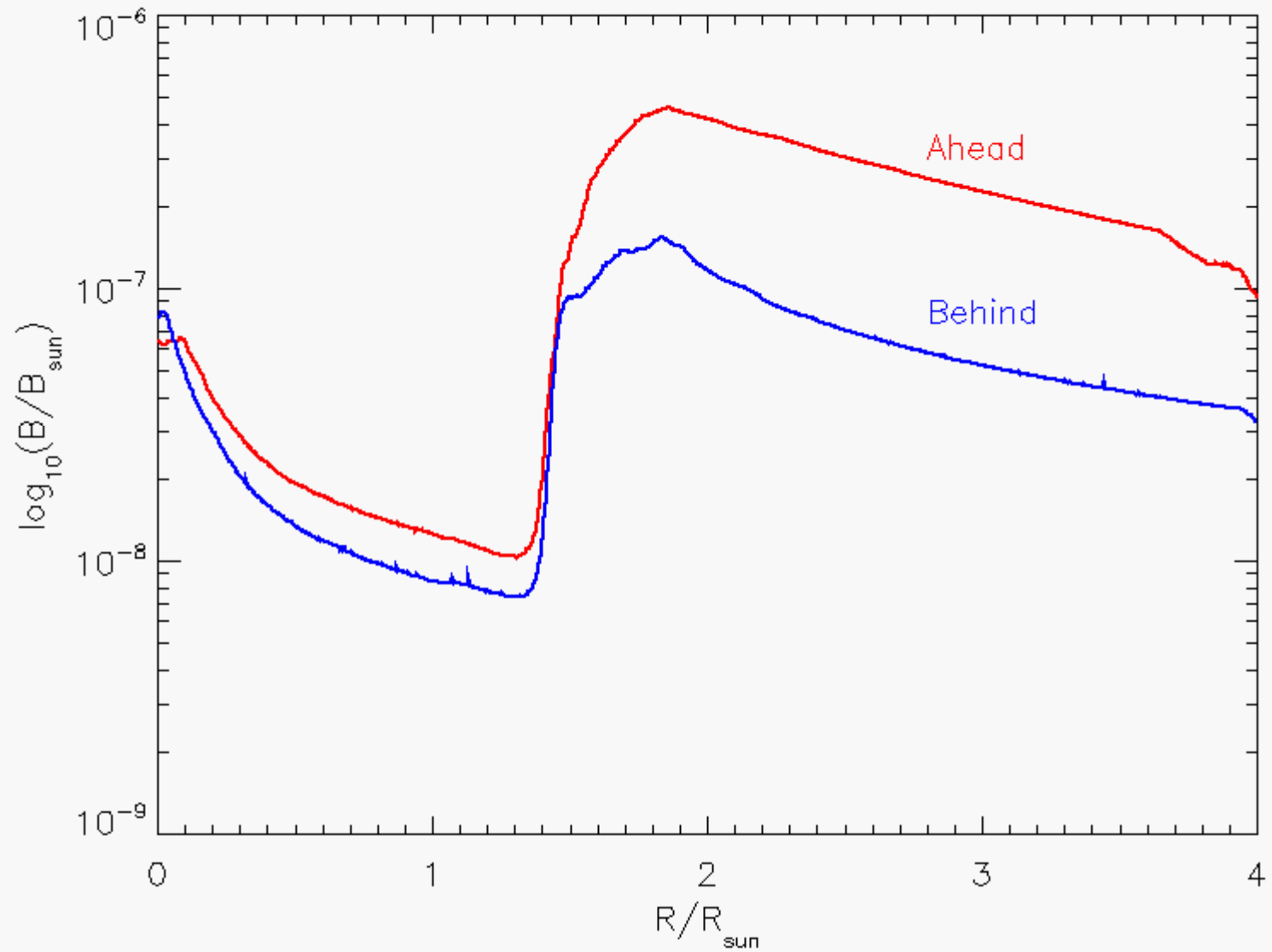
COR-1B

COR-1A

*Behind objective switched out at Cape—actually cleaner than preflight testing.*

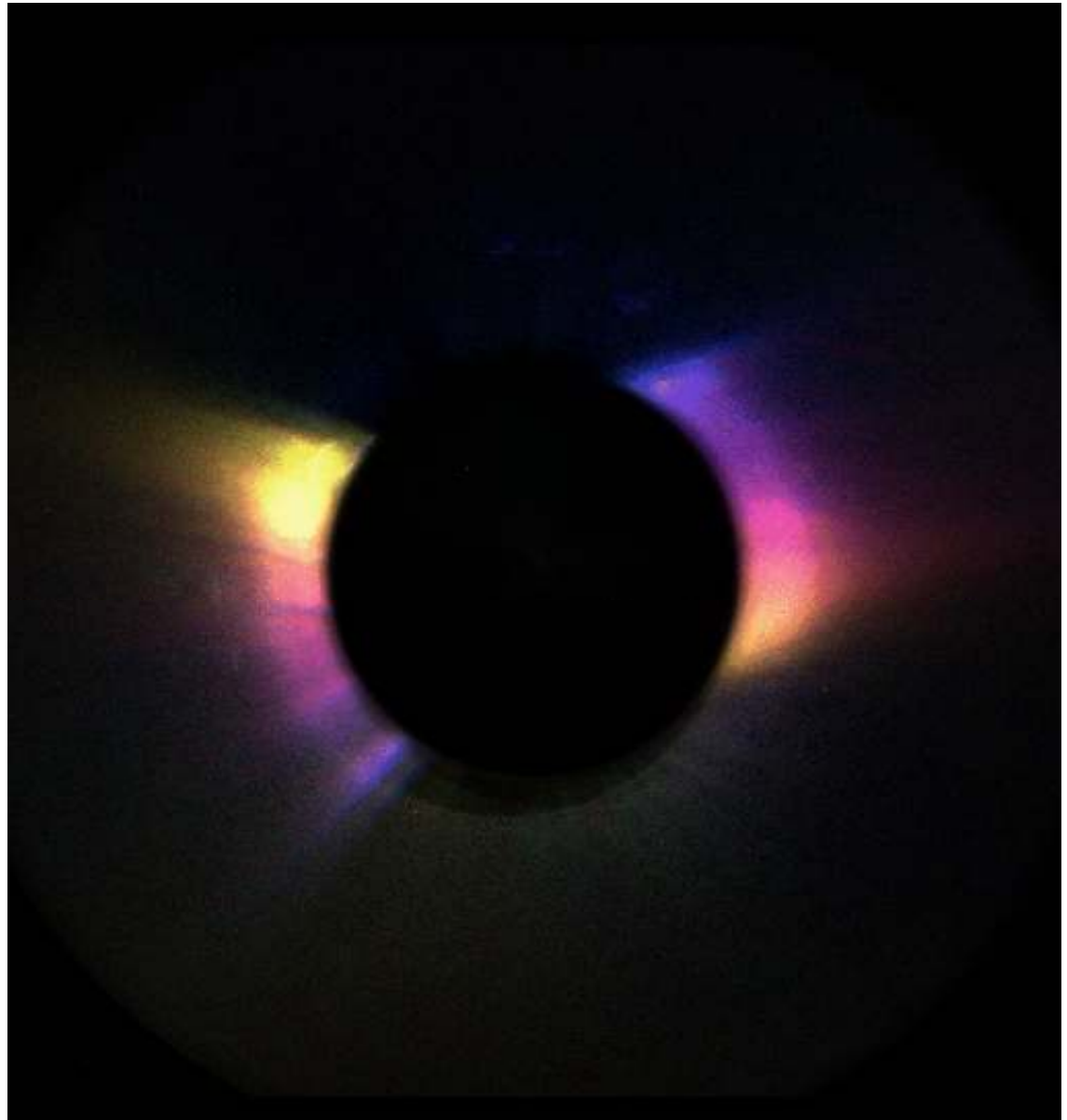


# Inflight performance



## Concept of Operations

- Three images are taken at polarizer positions of  $0^\circ$ ,  $120^\circ$ , and  $240^\circ$ .
- Combining the three images allows one to derive both the polarized brightness ( $pB$ ) and the total brightness ( $B$ ).
- The polarized brightness calculation rejects most of the stray light.

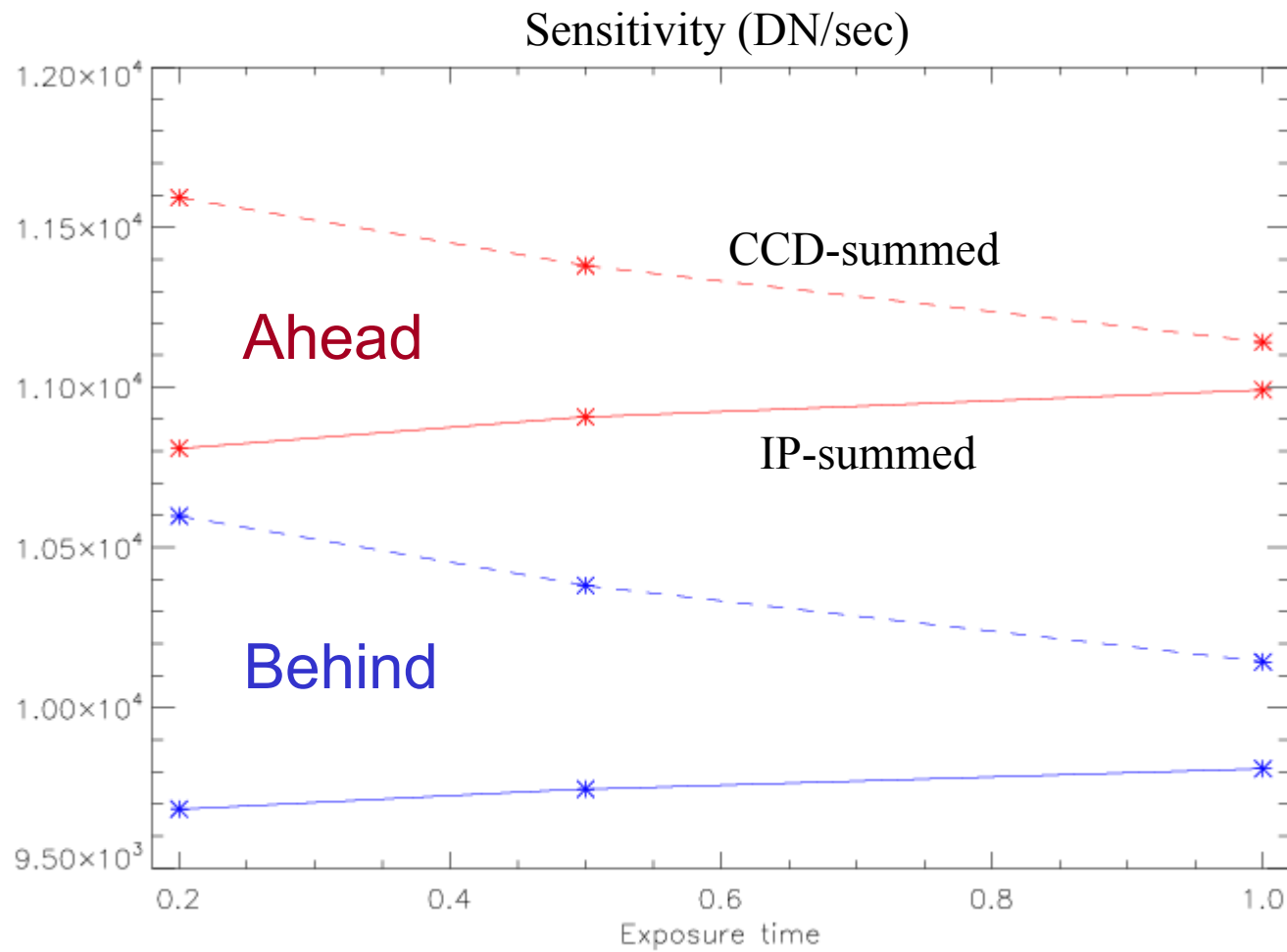


*Image showing 3 separate polarization components*



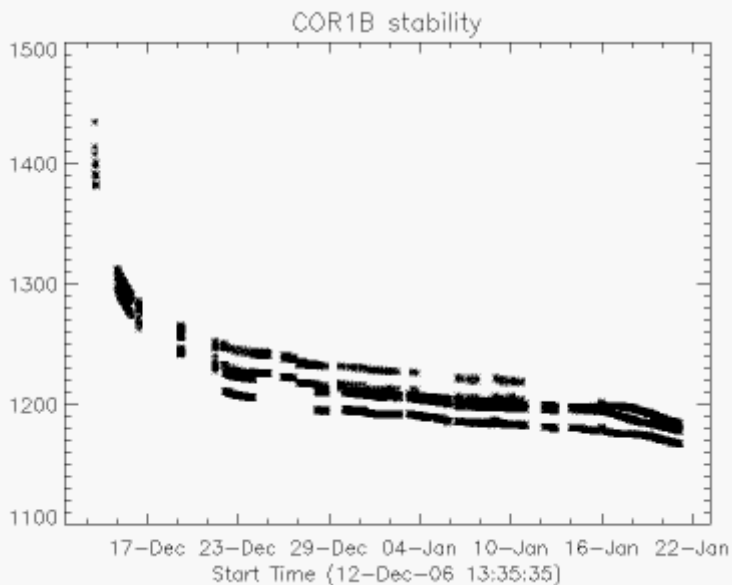
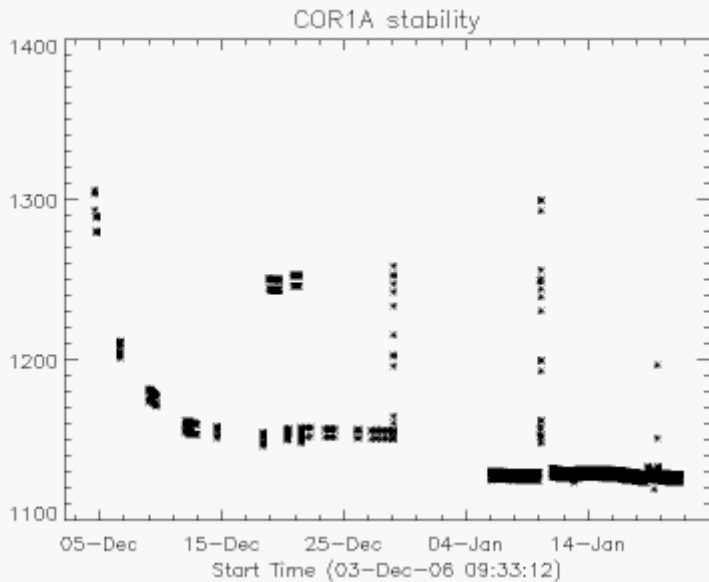
# Linearity

- Detectors on both COR1A and COR1B are slightly non-linear
- IP-summed  
~1%
- CCD-summed  
~3%
- Measured with two separate techniques
- Exposure time of 1.7 seconds chosen to keep well within linear range.

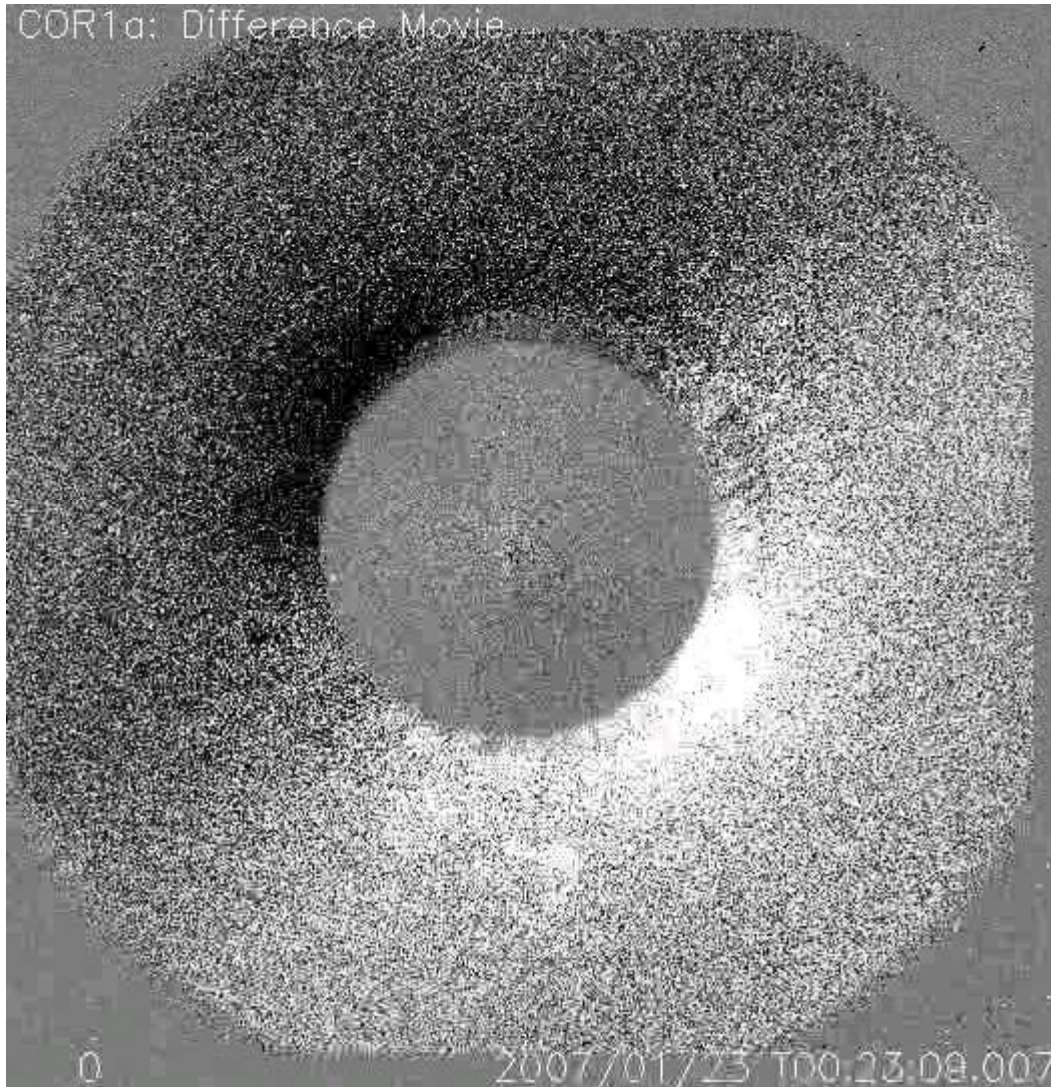


# Stability

- Both COR1A and COR1B have shown decreases in the scattered light since their doors were opened, by about 15%
- Only the diffuse scattered light shows a decrease—the discrete features remain constant
- COR1B shows some evolution between the 3 polarizer components.



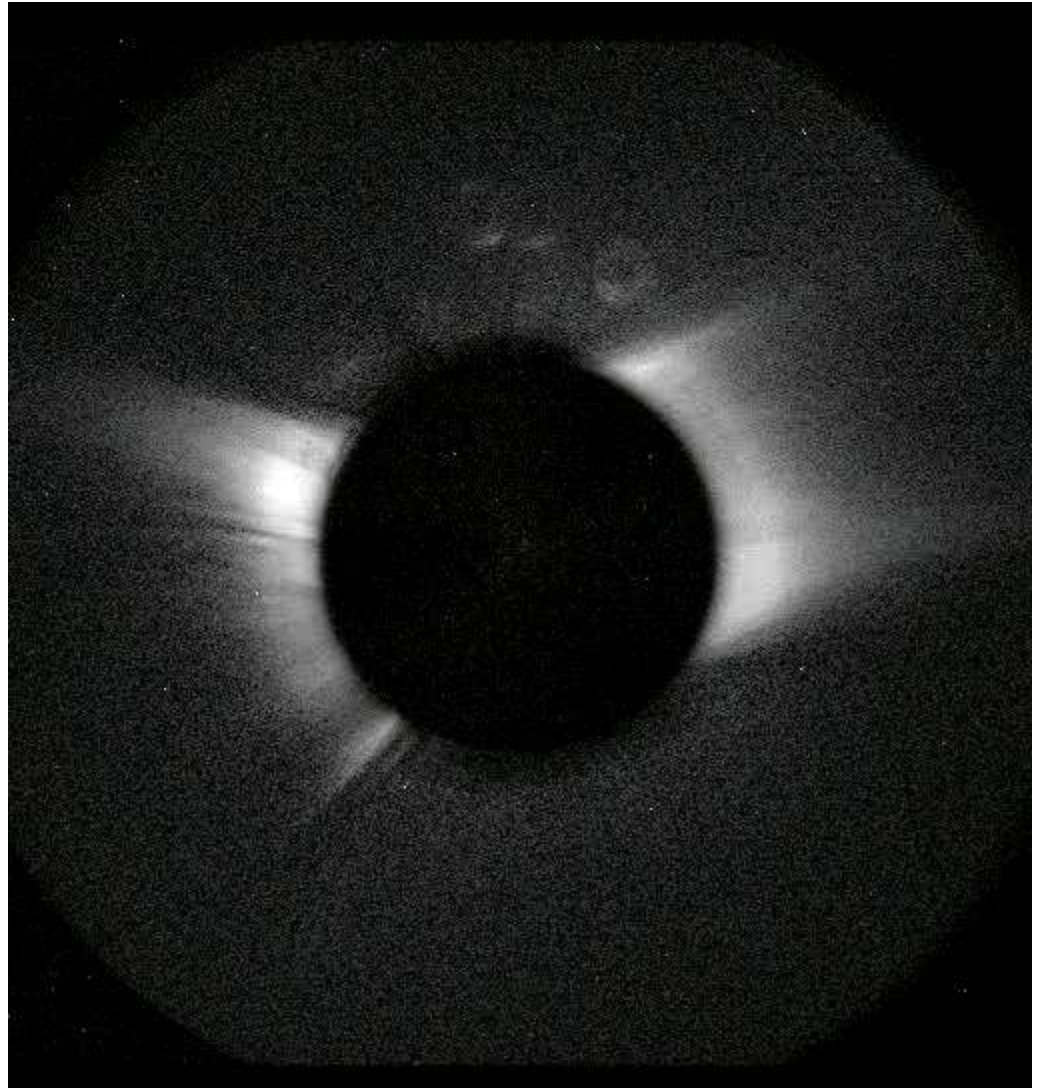
# Jitter Sensitivity



- Spacecraft jitter affects COR1 scattered light pattern.
- Spacecraft jitter greatly improved on Jan 23 (Ahead) and Jan 24 (Behind).
- Still studying how to model jitter effects in data.

# Roll Maneuvers

- Roll maneuvers allow the separation of instrumental and coronal effects.
  - Coronal hole assumed to be zero intensity
- Derived scattered light suitable for extracting  $pB$ 
  - $B$  affected more by instrumental evolution
  - Behind evolution also affecting  $pB$  calculation
- There are several roll maneuvers now on each spacecraft.



SWAVES roll on Ahead, Dec 18<sup>th</sup>



# Compression

- Image compression is required to be able to bring down data with sufficient cadence to see all CMEs.
- ICER is limited to a dynamic range of just over 13 bits.
- Dynamic range in COR1 is limited by scattered light
  - Top end limited by brightest part of the image, near occulter.
  - Bottom end limited by Poisson noise in fainter outer regions.
  - Resulting dynamic range is less than 13 bits for 2x2 binning for both COR1A and COR1B
- Strategy is to select a compression mode that keeps the digital noise below the Poisson noise.
  - Binning to 1024x1024 first improves statistics
    - Optics designed for 1024x1024 operation
  - Selected ICER 05 compression mode
  - Space weather: 128x128 binned with ICER 11



# Observing Plans

- Three polarizer positions ( $0^\circ$ ,  $120^\circ$ ,  $240^\circ$ ) taken in rapid sequence
- All images binned to  $1024 \times 1024$  resolution
- Currently planning on IP-binning for better linearity
  - May need to go to CCD-binning to reduce radiation-induced noise
- Images scaled to 13 bits and compressed with ICER 05
- Complete polarizer sequence repeated every 10 minutes
  - SSR2 data decreases cadence to 5 minutes for few hours

# Removing Scattered Light

- Polarized brightness ( $pB$ ) calculation removes much of the scattered light.
  - Still some residual scattered light
- Running and base difference movies also work well
  - Jitter sensitivity less for  $B$  than for  $pB$
- Other strategies include:
  - Removing model derived from calibration rolls
    - Works well for  $pB$
    - Instrument evolution limits effectiveness for  $B$
  - Monthly minimum image technique
    - Effect of instrument evolution not yet clear
  - Daily minimum image technique
    - Mainly effective for CMEs
- Above models are applied to each polarization component before combining into  $pB$

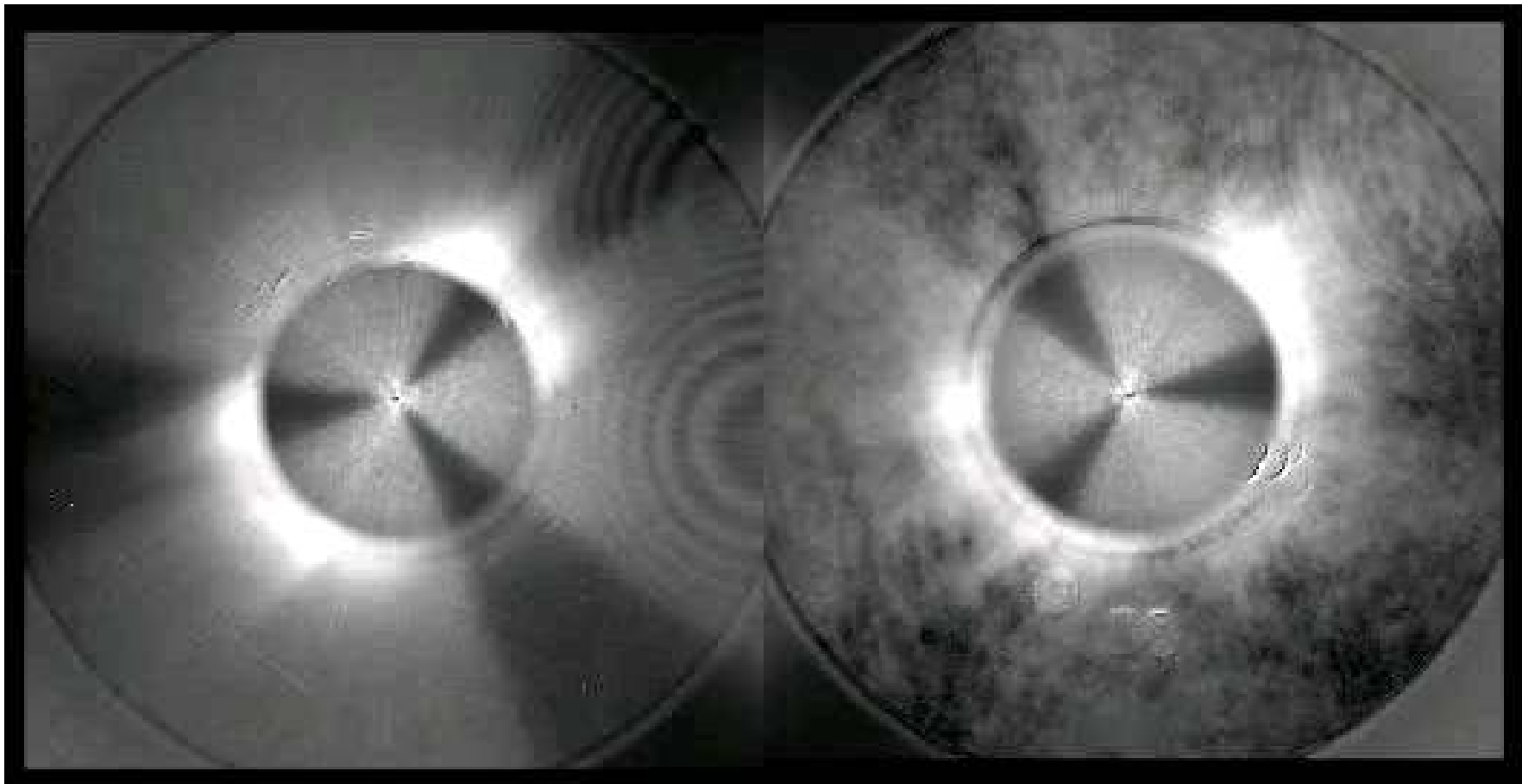
# Without Background Subtraction

- Most of the scattered light is removed by the  $pB$  calculation.

Behind

$pB$

Ahead



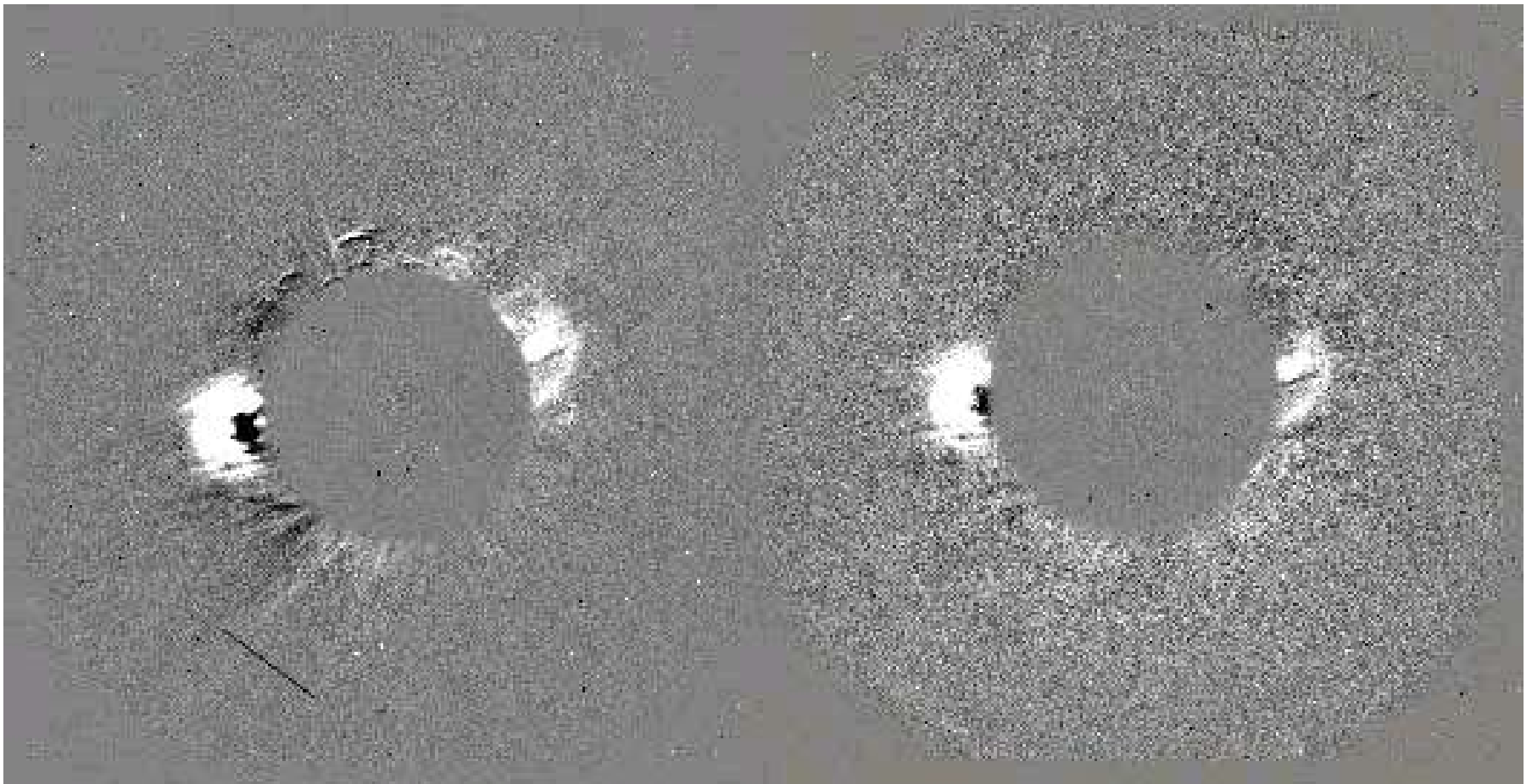
# Running Difference

- Running differences appear best in brightness images.

Behind

*B*

Ahead



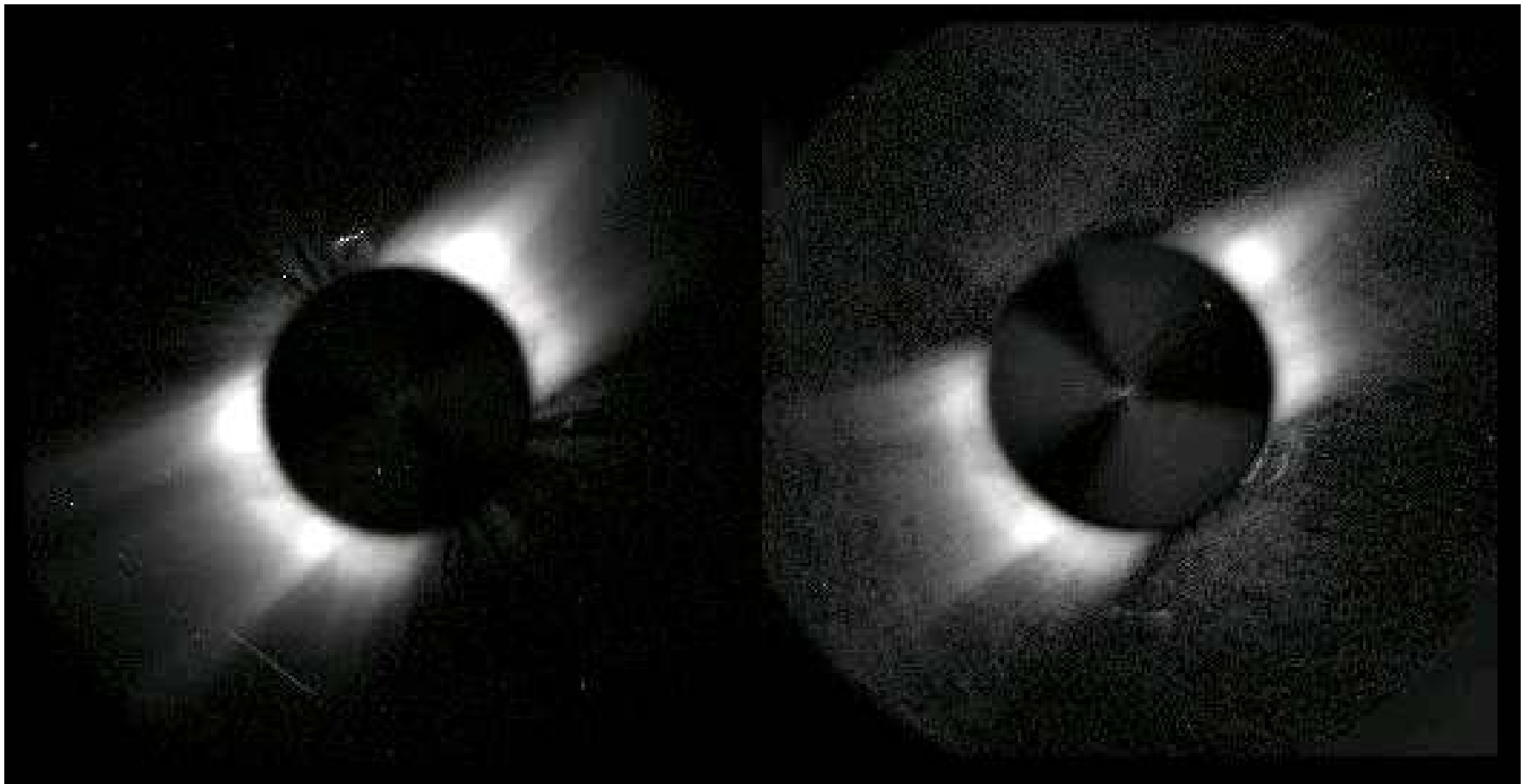
# Subtracting Rotation Model

- Most representative of corona. Instrument evolution so far restricts use to  $pB$ .

Behind

$pB$

Ahead





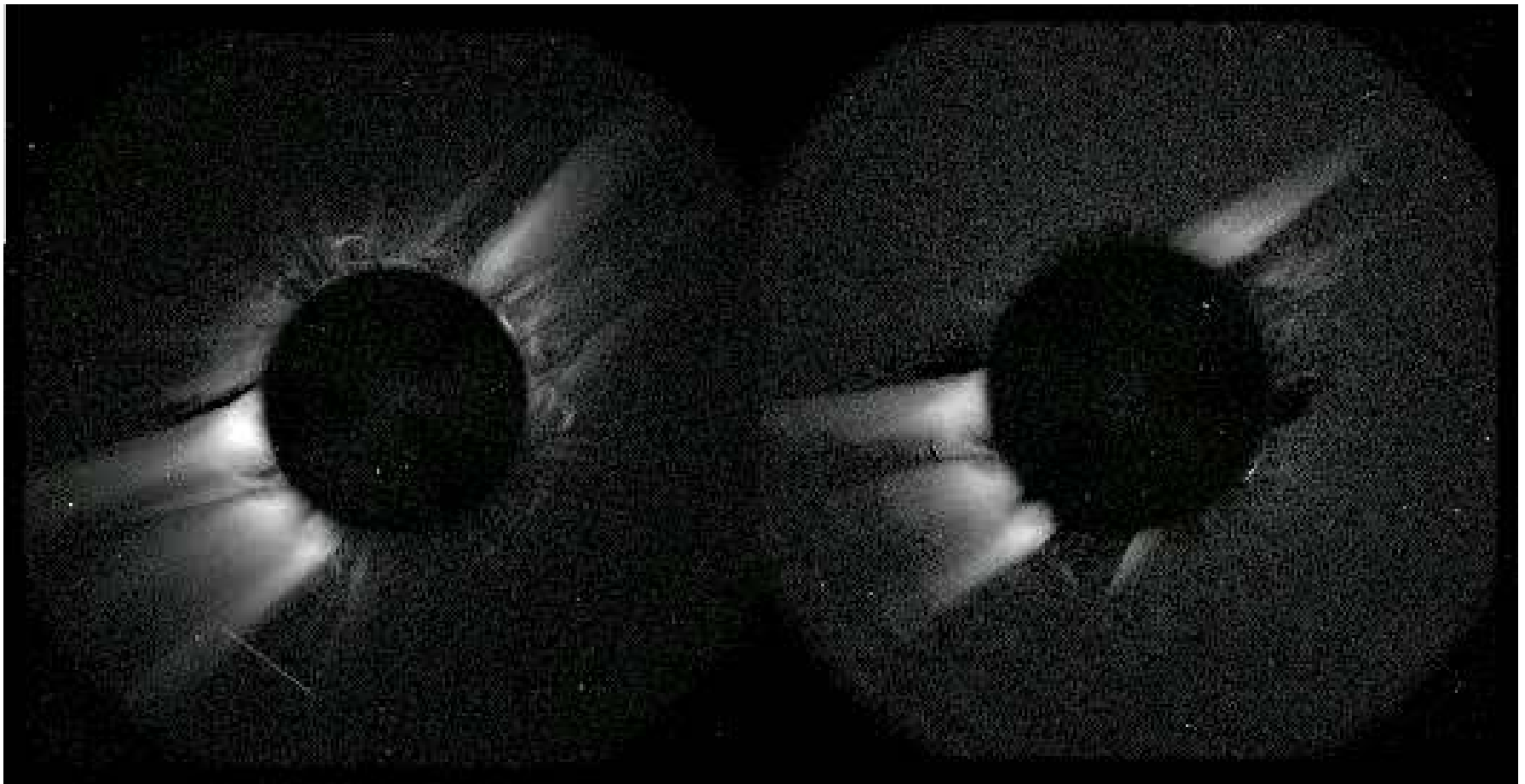
# Subtracting Daily Minimum

- Below is a demonstration of subtracting the daily minimum image from polarized brightness data

Behind

*pB*

Ahead



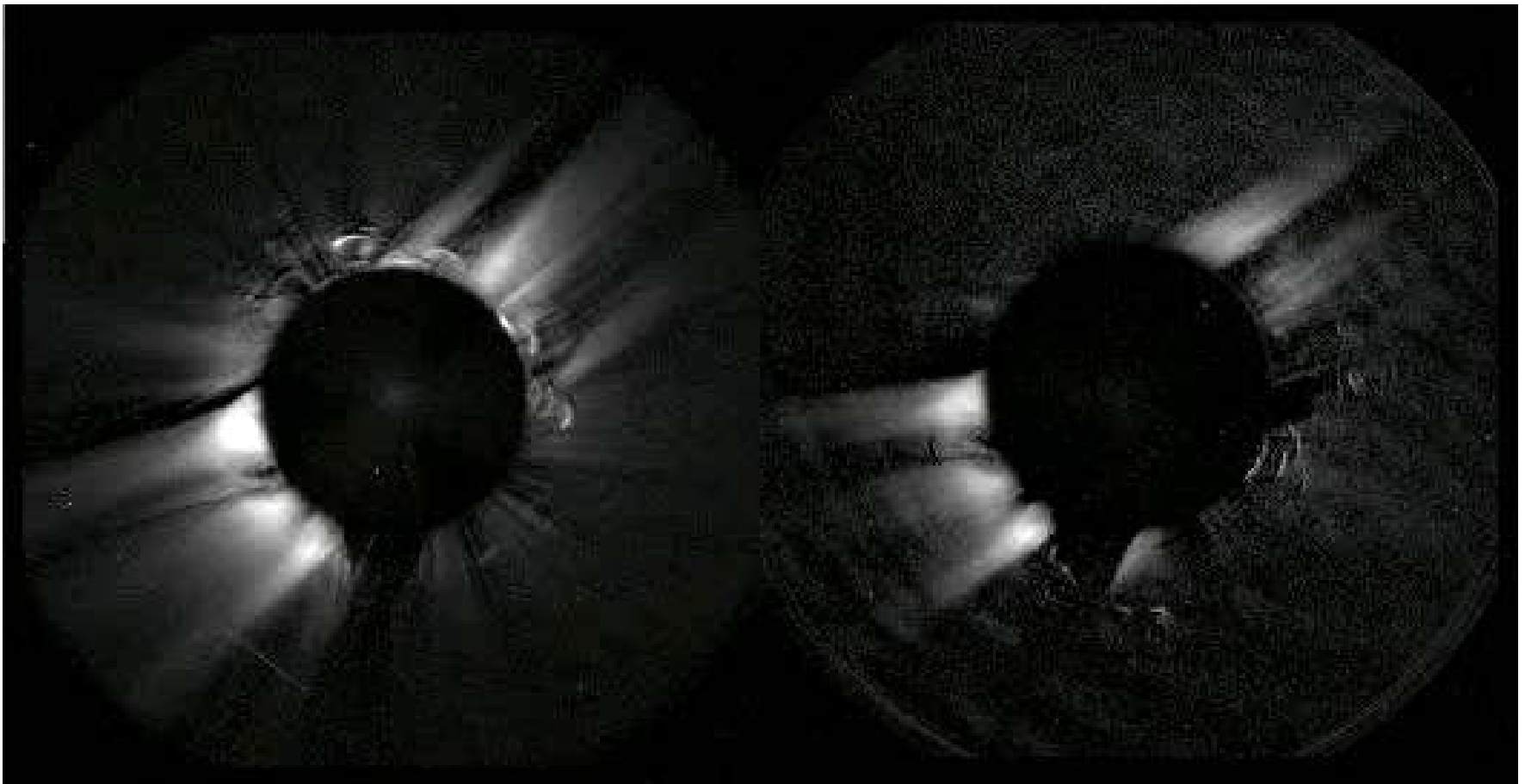
# Subtracting Daily Minimum

- It also works for total brightness. Some evolution in background can be seen for Ahead.

Behind

*B*

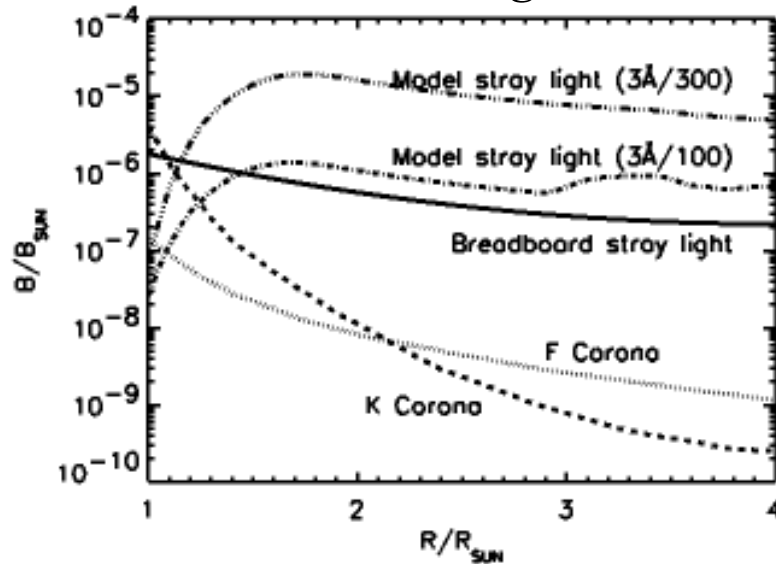
Ahead



Extra Slides

# Instrument Performance

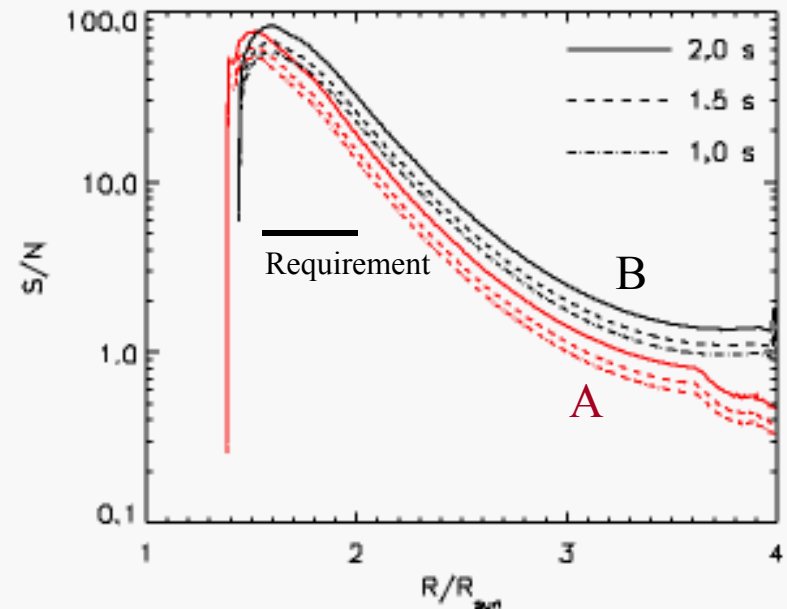
*Relative brightness*



- When the 3 polarization angles are combined, the pB of the K corona is recovered from the unpolarized background
- CMEs are visible from the occulter to the detector edge.

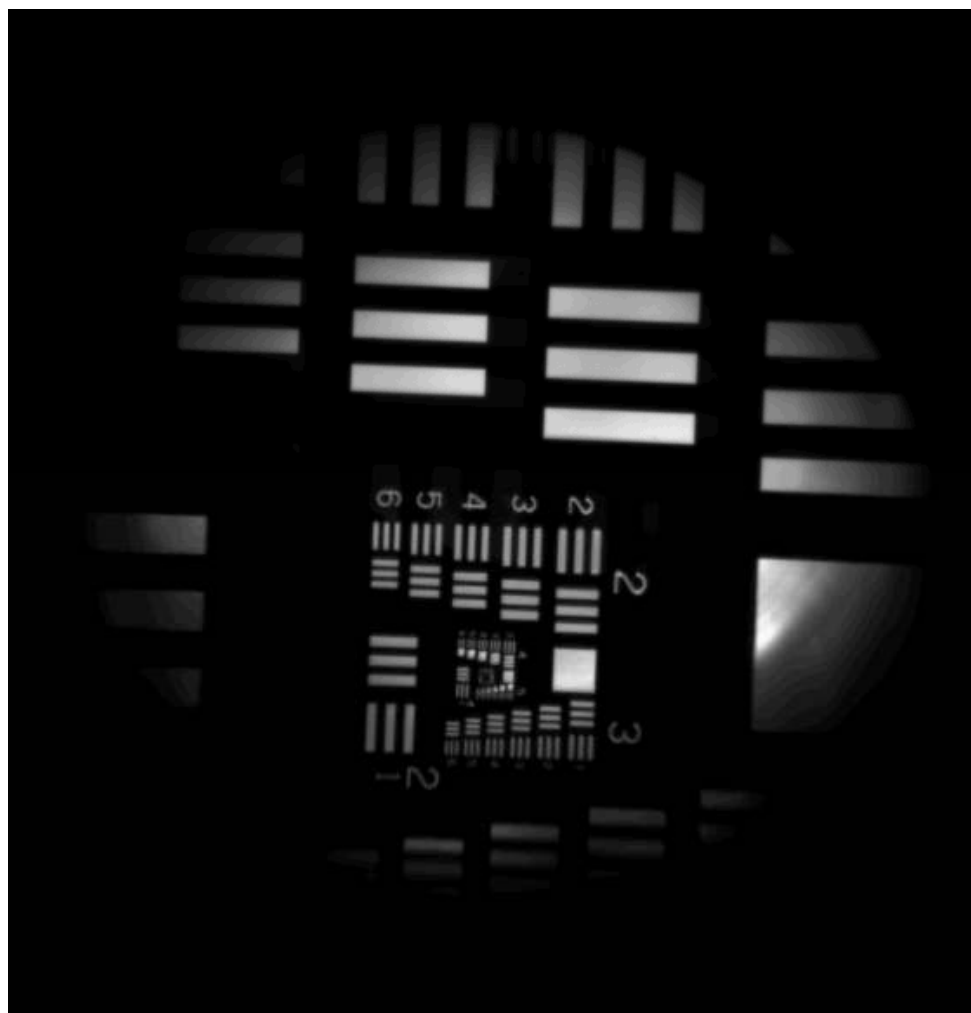
- The measured straylight is lower than the model predictions.
- The K corona is fainter than the stray light, but significantly brighter than the noise floor.

*Signal to noise ratio*



# Resolution

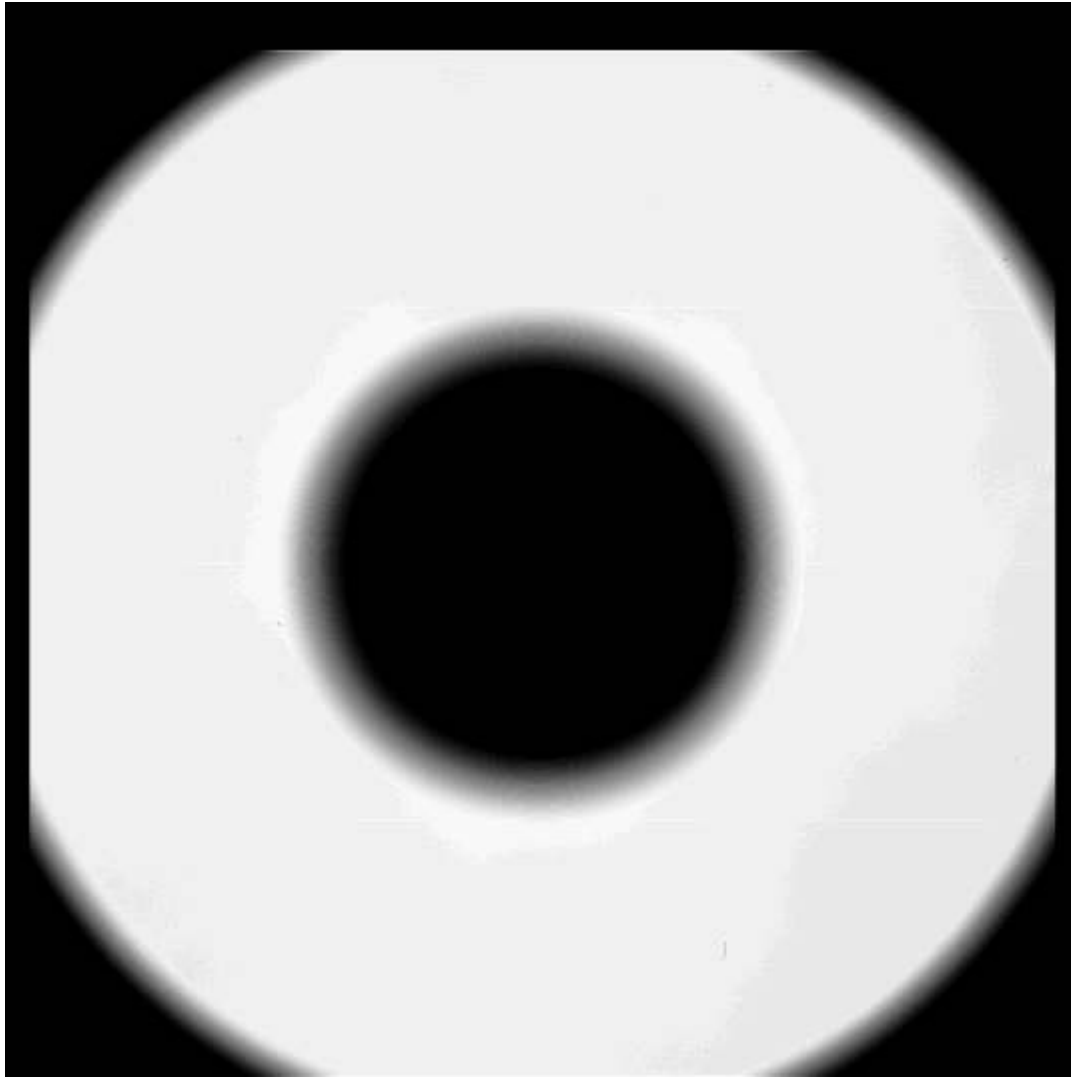
- Resolution tested by projecting Air Force resolution test target onto various portions of the detector.
- Measurements done in vacuum, to avoid problems with air vs. vacuum focal lengths.
- Were able to resolve with high contrast all the way down to the Nyquist frequency.



*Sample subfield image (COR-1A)*



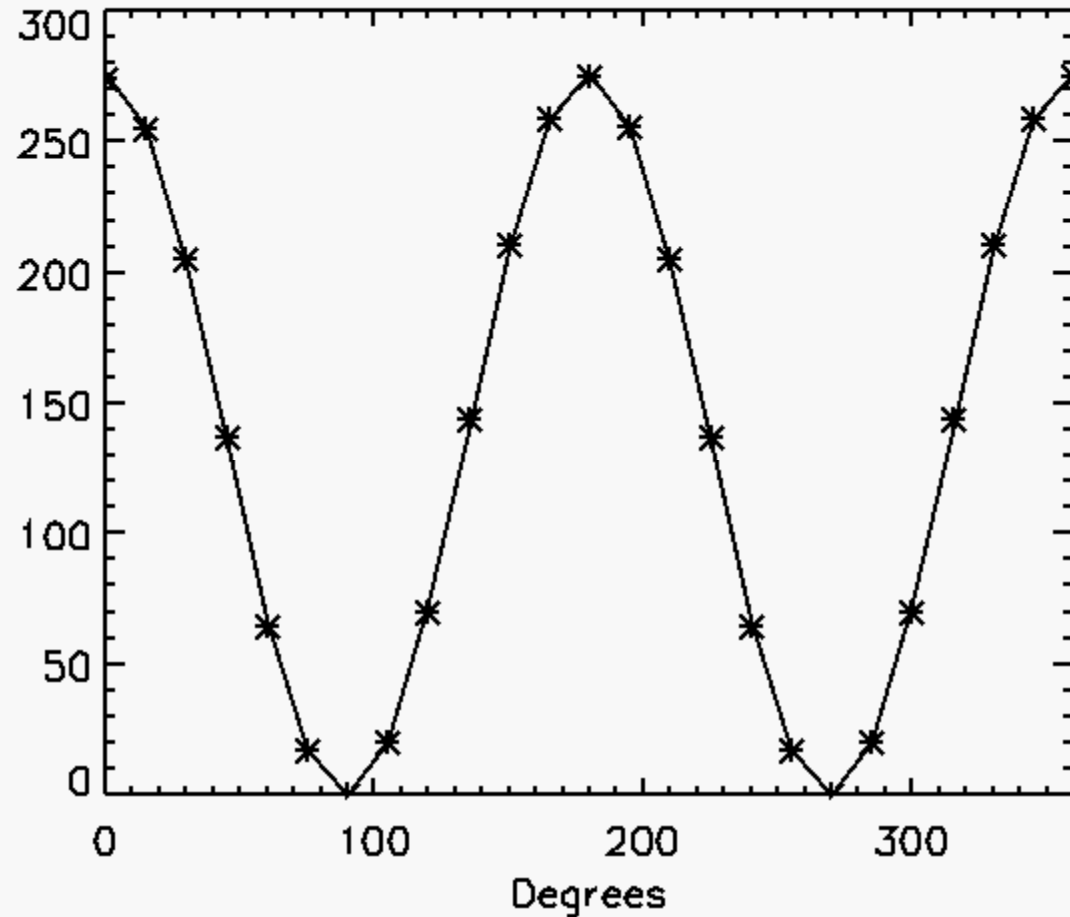
# Flat Field



- The field is highly flat, with discrete areas of vignetting near the occulter and camera aperture edges.
- The flat field is monitored in flight with the diffuser window mounted in the door.

# Polarization Response

- **Polarcor** linear polarizers provide better than 10,000:1 contrast ratio.
- Hollow core motor rotates polarizer in beam to angles  $0^\circ$ ,  $120^\circ$ , and  $240^\circ$  to derive polarized brightness.
- Rotation of polarizer moves image on detector by  $\sim 0.3$  pixels for both COR-1A & B. Minimized by putting slight tilt on polarizer.



*Measurements of polarization response compared to fitted curve (COR-1A)*